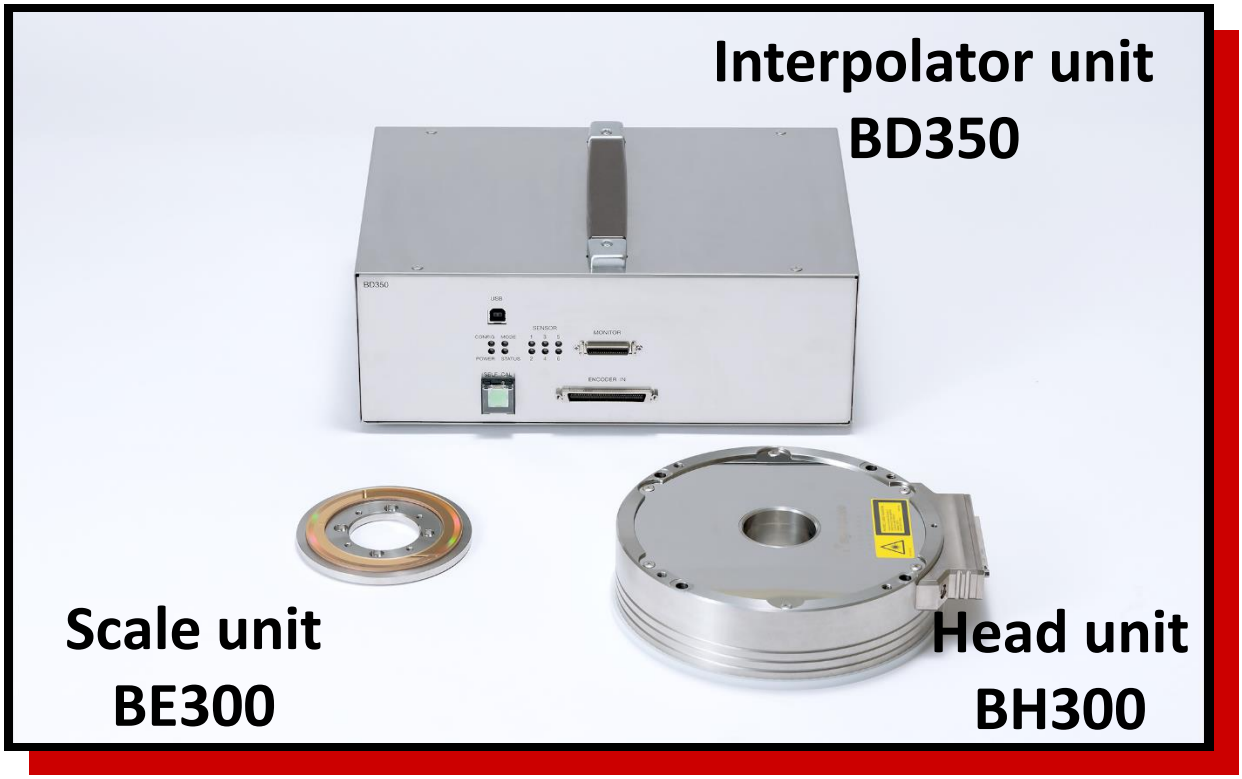
Magnescale

Angle calibration system

Newly Released by Magnescale



Self-calibrating Rotary Encoder System

SET-HD100

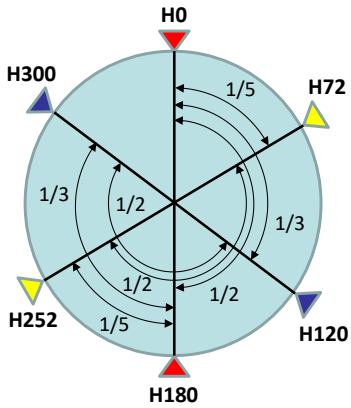
High angular accuracy	±0.1 arcsec achieved by unique Self-calibration function (Resolution: 0.0012 arcsec)
Traceability of accuracy	Qualified to the national primary standard by AIST (National Inst. of Advanced Industrial Science & Technology)
High repeatability	High repeatability in repeated measurements and for rotational direction
Easy installation	15 minutes only from installation to measurement
Handy measuring kit	Compact and easy to carry

Magnescale Co., Ltd.

Self-compensating algorithm for angle accuracy

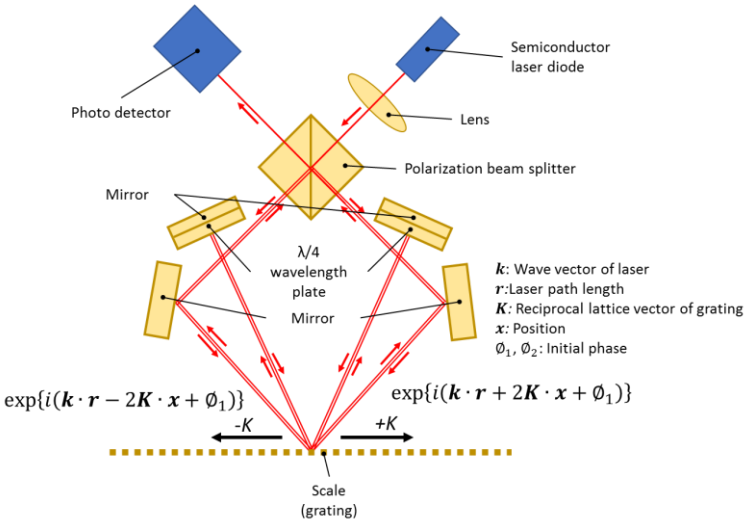
Intelligent encoder can compensate its own errors. Magnescale original self-calibration algorithm “VEDA-method” *1 enables higher order correction with less heads, achieving up to 30th order compensation with only 6 heads at world-class high accuracy.

*1 Patent application No.6386368



Compensation order：
2×3×5=30th

High resolution and stability by Laserscale

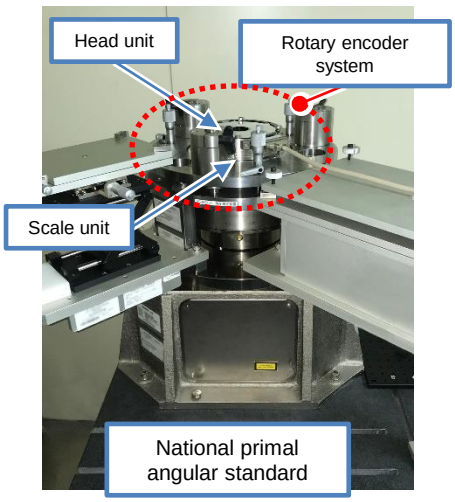


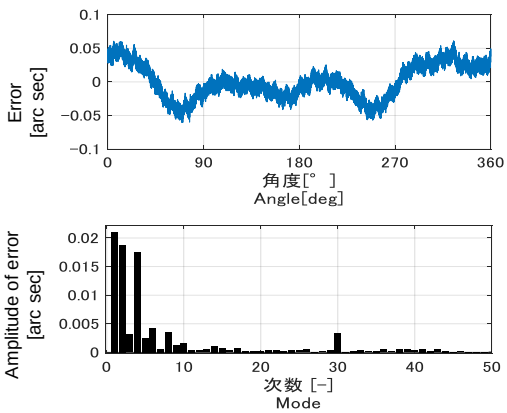
Laserscale allows high stability against environmental change such as pressure and temperature with the combination of high resolution, diffraction grating and a sensor head with symmetric optical path. Signal wavelength 1.24 arcsec = 6.0 μrad (250 nm on the circle of Ø42 scale) is electrically interpolated to the resolution of 0.0012 arcsec = 5.9 nrad (0.25 nm on Ø42) at the low noise level.

High accuracy and traceability

Accuracy is qualified against the primal national standard at AIST.
at Calibration : ±0.1 arcsec

Magnescale is certified by the National Institute of Technology and Evaluation (NITE) as an accredited calibration service provider. Magnescale will carry out JCSS calibration and issue a calibration certificate.



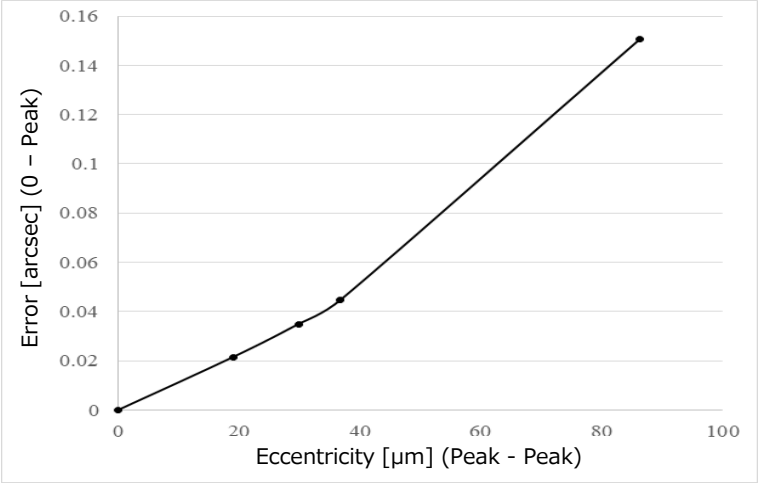


Example of accuracy measurement against national primal standard : ±0.061 arcsec

High repeatability on the measurement machine

Fine mechanical adjustment in the head unit keeps angle error from eccentricity at installation of a scale significantly low.
High accuracy in repeating measurement and in CW/CCW direction enables high repeatability
Non-contact design eliminates the effect from the encoder onto rotating axis of the measured target.

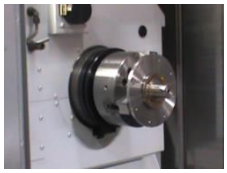
e.g. Eccentric response



Easy installation

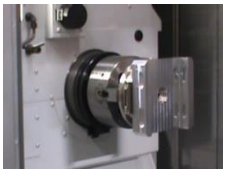
15 minutes from installation to measurement Remark: act. time depends on mounting conditions at customer site

Example of installation onto a horizontal machine



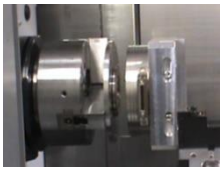
①Mount scale unit
Match the eccentricity of a scale and rotation axis
Insert positioning shaft

②Mount head unit
Adjust and mount the head to mechanical reference of inner diameter of a scale



③Mount attachment & fix to outer part
Install an attachment to fix the head unit onto the outer part

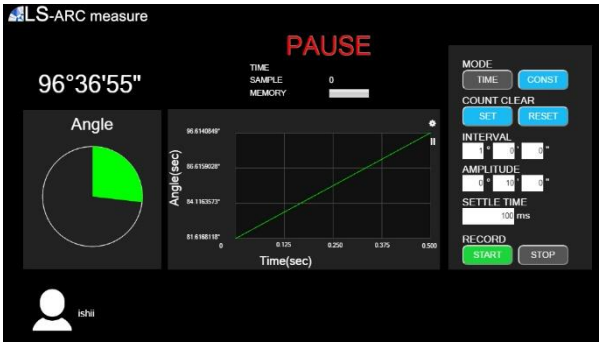
④Remove positioning shaft
Slide the head unit then remove a positioning shaft



⑤Adjust clearance
Adjust a clearance by moving a head unit toward the scale

Easy operation

No complex process needed for self-compensation.
Interpolator applies compensated value automatically and output accurate angular position by pressing a single switch.
Dedicated software generates angular data on a display and saves measured data.



e.g. display by dedicated software during measurement

Functions available by Magnescale software

- Real time data display
- Storage of measured data（TIME mode)
  Measurement at constant sampling of 20 kHz
  Suitable for servo vibration analysis and speed jitter evaluation
- Storage of measured data(CONSTANT mode)
  Data acquired at constant angle for accuracy measurement and saving compensation data

Portable measurement kit

Carry-on case is included to a standard package, which makes transportation easy and secures performance as an angular calibration system.

Head unit BH300

Scale unit BE300

Interpolator unit BD350

Recognition on outstanding technology

Magnescale won “2018 JSPE technology award” by Japan Society for Precision Engineering for introduction of the rotary system with original, self-compensation algorism. Several research papers to explain the principle and development of the algorism were also published in journals of JSPE as well as Advanced Mechanical Design, Systems and Manufacturing.

(1) N. Ishii, K. Taniguchi, K. Yamazaki and H. Aoyama: Development of super-accurate angular encoder system with multi-detecting heads using VEDA method, Journal of Advanced Mechanical Design, Systems, and Manufacturing, **12** (2018).

(2) N. Ishii, K. Taniguchi, K. Yamazaki and H. Aoyama: Super-Accurate Angular Encoder System with Multi-Detecting Heads Using VEDA Method, Journal of the Japan Society for Precision Engineering, **84** (2018). 717-723.

Specifications

Item	Specification	Item	Specification
Detecting radius	41.723 mm	Number of sensor	6 sensors / unit
Maximum rotary response speed	10 min^{-1}	Light source	Semiconductor laser × 6
Number of source signals	2^{20} (1,048,576) / revolution		Wave length790 nm, 5 mW or less / sensor
Source signal resolution	1.236 arcsec	Radiation power	EN60825: class 3B, JIS: class 3B, DHHS: class IIIb
Accuracy	at Calibration : ±0.1 arcsec Mounting tolerance : ±0.2 arcsec	Operating temperature range	+10 to +30 ℃ (no condensation)
Reference point position	1 point	Storage temperature range	0 to +50 ℃ (no condensation)
Output format	USB 2.0	Power supply	DC 20 to 24 V / 5 A (Max. 8 A)
Number of interpolations	2^{10} (1,024) / revolution	Dimension/Mass	Scale unit: Φ100×H8.5 mm / 300 g or less
Number of output divisions	2^{30} (1,073,741,824) / revolution		Head unit: Φ180×H46 mm / 3.8 kg or less
Output resolution	0.0012 arcsec		Interpolator unit: 298×210×110 mm / 5 kg or less

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